

## *Locating Lines and Hyperplanes*

# Fermat – Torricelli – Weberov problem

$$I = \{1, \dots, m\}$$

$$\Lambda = \{T_i(x_i, y_i) \in \mathbb{R}^2 : i \in I\}$$

$$w = \{w_i > 0 : i \in I\}, \quad W = \sum_{i=1}^m w_i$$

**Median problem:** odrediti  $T_0(x_0, y_0) \in \mathbb{R}^2$  koji je rjesenje problema

$$\sum_{i=1}^m w_i d(T_i, T) \longrightarrow \min_{T \in \mathbb{R}^2}$$

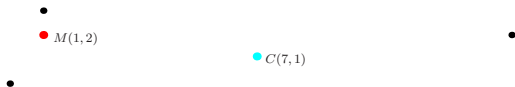
**Problem centra:** odrediti  $T_0(x_0, y_0) \in \mathbb{R}^2$  koji je rjesenje problema

$$\max_{i=1, m} w_i d(T_i, T) \longrightarrow \min_{T \in \mathbb{R}^2}$$

**Weiszfeld algoritam (1936) za:**  $d^{(2)}(T, T_i) = \sqrt{(x - x_i)^2 + (y - y_i)^2} =: d_i(x, y)$

**Manhattan udaljenost za:**  $d^\infty(T, T_i) = |x - x_i| + |y - y_i|$

d\_1: Medijan (crveno), Centar (zeleno)



d\_2: Medijan (crveno), Centar (zeleno)



d\_infty: Medijan (crveno), Centar (zeleno)



$\Gamma$  – objekt (facility), primjerice: točka, pravac (hiperravnina), segment, poligonalna linija, kruznica, graf

$$\sum_{i=1}^m w_i d(T_i, \Gamma) \longrightarrow \min_{\Gamma} \quad \text{— medijan problem ili problem sume}$$

$$\max_{i=1, m} w_i d(T_i, \Gamma) \longrightarrow \min_{\Gamma} \quad \text{— problem maksimuma ili problem centra}$$

### Primjene:

- autoput, željeznička pruga (objekti – gradovi, težine – broj stanovnika)
- trasa kanala za odvodnju i navodnjavanje, problem sirine skupa

### Drugi pristupi:

- Numericka matematika – Computational Geometry ( $l_1$  i  $l_\infty$  problem aproksimacije)
- Statistika (robust statistics, LAD regression, median problem, orthogonal regression)

**$p$ -norma na  $\mathbb{R}^n$ :**

$$x \in \mathbb{R}^n, \quad \|x\|_p = \left( \sum_{i=1}^n w_i |x_i|^p \right)^{1/p}$$
$$\|x\|_\infty = \max_{i=1,n} w_i |x_i|$$

**$p$ -udaljenost na  $\mathbb{R}^n$ :**

$$x, y \in \mathbb{R}^n, \quad d^p(x, y) = \|x - y\|_p = \left( \sum_{i=1}^n w_i |x_i - y_i|^p \right)^{1/p}$$
$$d^\infty(x, y) = \|x - y\|_\infty = \max_{i=1,n} w_i |x_i - y_i|$$

$p = 2$ : Euklidska norma i udaljenost

$p = 1$ : Manhattan (pravokutna) norma i udaljenost

$p = \infty$ : Cebisevljeva max norma i udaljenost

**Jedinicna kuglina ljuska na  $\mathbb{R}^n$ :**

$$K^p(0, 1) = \{x \in \mathbb{R}^n : d^p(0, x) = 1\} = \{x \in \mathbb{R}^n : \|x\|_p = 1\}$$

**Ekstremne tocke jedinicne kugline ljuske na  $\mathbb{R}^n$ :**

$$E(K^1) = \{e_i, -e_i : i = 1, \dots, n\}$$

$$E(K^\infty) = \{(s_1, \dots, s_n) \in \mathbb{R}^n : s_i \in \{-1, 1\}\}$$

**Veza  $d^1 \longleftrightarrow d^\infty$  na  $\mathbb{R}^2$ :**

$$d^\infty(x, y) = d^1(Tx, Ty)$$

$$d^1(x, y) = d^\infty(T^{-1}x, T^{-1}y)$$

$$T = A \cdot U, \quad A = \frac{1}{\sqrt{2}}\mathcal{I}, \quad U - \text{rotacija za kut } (-\frac{\pi}{4})$$

$$A(e) = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad U(e) = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}, \quad T(e) = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}$$

**Hiperravnina** zadana vektorom normale  $\mathbf{n} = (s_1, \dots, s_n)^T \in \mathbb{R}^n$ ,  $\mathbf{n} \neq 0$  i parametrom  $b \in \mathbb{R}$  :

$$H_{\mathbf{n},b} := \{x \in \mathbb{R}^n : (x, \mathbf{n}) + b = 0\}, \quad (x, \mathbf{n}) = x_1 s_1 + \dots + x_n s_n.$$

**Hiperravnine u  $\mathbb{R}^2$**  zadana vektorom normale  $\mathbf{n} = (a, b)^T \in \mathbb{R}^2$ ,  $a^2 + b^2 \neq 0$  i parametrom  $c \in \mathbb{R}$  :

$$p_{a,b,c} := \{(x, y) \in \mathbb{R}^2 : ax + by + c = 0\}, \quad - \text{pravac s koeficijentom smjera } \left(-\frac{a}{b}\right) \in \mathbb{R} \cup \{\infty\}.$$

Skup svih pravaca u ravnini moze se jednoznacno opisati s

$$ax + by + c = 0, \quad a^2 + b^2 = 1, \quad (1)$$

i rastaviti na dva disjunktna podskupa:

**( $b = 0$ ) Vertikalni pravci:**  $p_{-1,0,c}$ , tj.  $x = c$

**( $b \neq 0$ ) Ne-vertikalni pravci:**  $p_{a',-1,b'}$ , tj.  $y = a'x + b'$

Hiperravninu  $H$  definira particiju skupa  $\mathbb{R}^n = H \cup B_H^- \cup B_H^+$ .

**Horizontalna udaljenost na  $\mathbb{R}^n$ :**

$$d_h(x, y) = \begin{cases} |y_1 - x_1|, & x_i = y_i, i = 2, \dots, n \\ \infty, & \text{inace} \end{cases}$$

**Vertikalna udaljenost na  $\mathbb{R}^n$ :**

$$d_v(x, y) = \begin{cases} |y_n - x_n|, & x_i = y_i, i = 1, \dots, n - 1 \\ \infty, & \text{inace} \end{cases}$$

## Primjer

Udaljenost  $d_v$  tocke  $T_0(x_0, y_0)$  do ne-vertikalnog pravca  $p_{a,-1,b}$  je

$$\begin{aligned} d_v(T_0, p) &= \min_{T \in p} d_v(T_0, T) \\ &= d_v(T_0, (x_0, ax_0 + b)) \\ &= |ax_0 + b - y_0| \end{aligned}$$

**Veza  $d_h \longleftrightarrow d_v$  na  $\mathbb{R}^2$ :**

$$d_v(x, y) = d_h(Tx, Ty)$$

$$d_h(x, y) = d_v(Tx, y)$$

$$T - \text{rotacija za kut } \left(-\frac{\pi}{2}\right), \quad T(e) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

## Lema

Let  $(w_i, y_i)$ ,  $i \in I$ ,  $I = \{1, \dots, m\}$ ,  $m \geq 2$ , be the data, whereby  $y_1 \leq y_2 \leq \dots \leq y_m$  are real numbers, and  $w_i > 0$  are corresponding weights, and  $W = \sum_{i=1}^m w_i$ . Denote

$$\nu_0 = \max \left\{ \nu \in I : \sum_{i=1}^{\nu} w_i \leq \frac{W}{2} \right\}.$$

Furthermore, let  $F : \mathbb{R} \rightarrow \mathbb{R}$  be a function defined by the formula

$$F(\alpha) = \sum_{i=1}^m w_i |y_i - \alpha|. \quad (2)$$

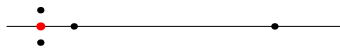
- (i) If  $\sum_{i=1}^{\nu_0} w_i < \frac{W}{2}$ , then the minimum of the function  $F$  is attained at the point  $\alpha^* = y_{\nu_0+1}$ .
- (ii) If  $\sum_{i=1}^{\nu_0} w_i = \frac{W}{2}$ , then the minimum of the function  $F$  is attained at every point  $\alpha^*$  from the segment  $[y_{\nu_0}, y_{\nu_0+1}]$ .

**Primjedba.** Primijetite da kao posljedica ove leme neposredno slijedi **pseudo-halving property** podataka  $(w_i, y_i)$ ,  $i \in I$ , pa možemo reći da je median ovih podataka svaki broj  $\alpha^*$  za kojeg vrijedi

$$\sum_{y_i < \alpha^*} w_i \leq \frac{W}{2} \quad \text{and} \quad \sum_{y_i > \alpha^*} w_i \leq \frac{W}{2}. \quad (3)$$



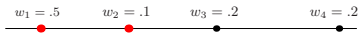
$$\frac{W}{2} = 2.5$$



$$\frac{W}{2} = 2.5$$



$$\frac{W}{2} = 2$$



$$w_1 = .5$$

$$w_2 = .1$$

$$w_3 = .2$$

$$w_4 = .2$$

$$\frac{W}{2} = .5$$

# Hiperplane location problem

**Med 1 (Weak incidence property):** postoji optimalna median hiperravnina koja prolazi kroz  $n$  afino nezavisnih tocaka iz  $\Lambda$ ;

**Med 2 (Pseudo-halving property):** za svaku optimalnu median hiperravninu  $H$  vrijedi

$$\sum_{T_i \in B_H^-} w_i \leq \frac{W}{2} \quad \text{and} \quad \sum_{T_i \in B_H^+} w_i \leq \frac{W}{2};$$

**Cen 1 (Weak blockedness property):** postoji optimalna max (centar) hiperravnina  $H$  koja ima svojstvo da je barem  $n + 1$  tocaka iz  $\Lambda$  tezinski maksimalno udaljeno od  $H$ ;

**Cen 2 (Paralel facets property):** ako je  $w_1 = \dots = w_m$ , onda postoji optimalna max (centar) hiperravnina koja je paralelna stranici konveksne ljuske tocaka skup  $\Lambda$ ;

**Cen 1' (Modified weak blockedness property):** postoji optimalna max (centar) hiperravnina  $H$  koja ima svojstvo da je  $n + 1$  afino nezavisnih tocaka iz  $\Lambda$  tezinski maksimalno udaljeno od  $H$ ;

# Line location with vertical distances

## Theorem

Let  $I = \{1, \dots, m\}$ ,  $m \geq 2$  be a set of indices,  $\Lambda = \{T_i(x_i, y_i) \in \mathbb{R}^2 : i \in I\}$  a set of points in the plane, such that  $\min_{i \in I} x_i < \max_{i \in I} x_i$ , and  $w_i > 0$  corresponding data weights. Then

- (i) there exists the best weighted LAD-line  $f(x) = a^*x + b^*$  which passes through at least two different points from  $\Lambda$ ;
- (ii) the best weighted LAD-line  $f(x) = a^*x + b^*$  is pseudo-halving

$X$  – skup svih točkaka i pravaca u ravnini  $M$ ;  
 $\mathcal{A} : X \rightarrow X$  – preslikavanje, zadano na sljedeći način:

$$\mathcal{A}(p_{a,-1,b}) = (a, b)$$

$$\mathcal{A}(T_0(x_0, y_0)) = q_{-x_0, -1, y_0}$$

**Vrijedi:**

$$d_v(T_0, p) = d_v(\mathcal{A}(T_0), \mathcal{A}(p))$$

$$d_v(T_0, p) = |ax_0 + b - y_0| = |-ax_0 + y_0 - b|$$

$$= d_v(q_{-x_0, -1, y_0}, (a, b))$$

$$= d_v(\mathcal{A}(T_0), \mathcal{A}(p))$$

**Vrijedi:**

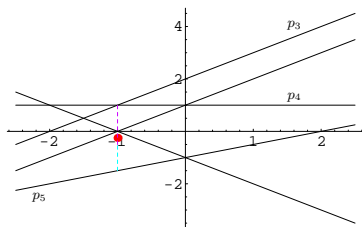
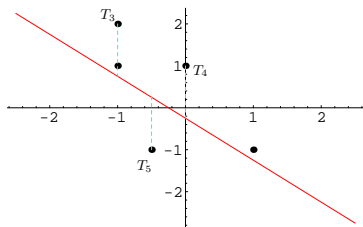
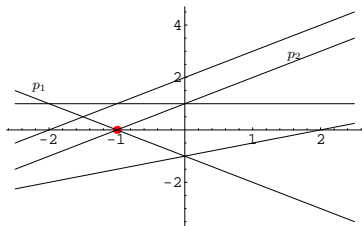
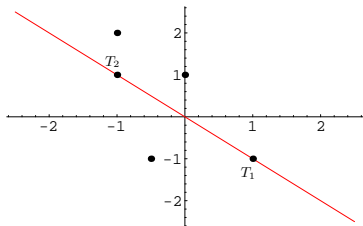
$$\sum_{i=1}^m d_v(T_i, p) = \sum_{i=1}^m d_v(\mathcal{A}(T_i), \mathcal{A}(p)) \quad \cdots \quad l_1$$

$$\max_{i=1,m} d_v(T_i, p) = \max_{i=1,m} d_v(\mathcal{A}(T_i), \mathcal{A}(p)) \quad \cdots \quad l_\infty$$

$\{\{1, -1\}, \{-1, 1\}, \{-1, 2\}, \{0, 1\}, \{-0.5, -1\}\}$

Median (l.1)  $\{3.5, \{a \rightarrow -1, b \rightarrow 0\}\}$

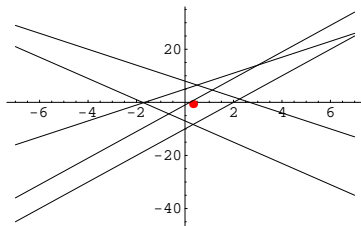
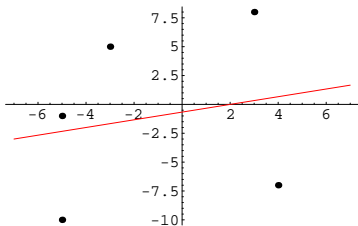
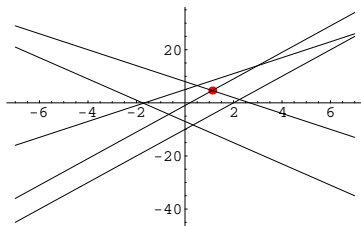
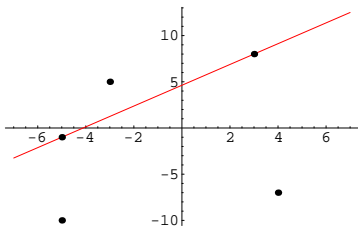
Center (l.infty)  $\{1.25, \{a \rightarrow -1., b \rightarrow -0.25\}\}$



$\{-5, -1\}, \{4, -7\}, \{-3, 5\}, \{3, 8\}, \{-5, -10\}$

$\{28.875, \{a \rightarrow 1.125, b \rightarrow 4.625\}\}$

$\{7.66667, \{a \rightarrow 0.333333, b \rightarrow -0.666667\}\}$





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